

Impact of Traffic Signal Synchronization on Reducing Urban Traffic Delays in Kathmandu Valley

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Abstract: - Traffic congestion in rapidly growing cities like Kathmandu Valley has become a major challenge. Due to the lack of an integrated traffic signal system, delays are common at important intersections like Maitighar, Thapathali, and Singhadurbar, particularly during peak hours. With increased vehicle numbers and inadequate infrastructure development, traffic congestion has worsened, adding to longer travel times, environmental pollution, and economic inefficiencies. Synchronization of traffic signals, where the timing of signals is coordinated over a number of intersections, has shown potential for reducing delays and optimizing flow.

This review looks to explore the impact that traffic signal synchronization has on reduction in urban traffic delays within Kathmandu Valley. In this study, findings from a synthesis of global research relating to adaptive control systems and signal synchronization identify strategies already in place that have considerably reduced congestion in other urban settings. Signal synchronization can reduce vehicle stops, waiting times, and fuel consumption drastically, which is very much necessary for improving overall traffic management.

The review has looked at existing methodologies to establish how synchronization could be effectively done at key intersections in Kathmandu Valley to alleviate congestion. The expected outcomes will be smooth traffic flow, reduced travel times, and improved efficiency at intersections. Additionally, synchronized signal systems could have other secondary benefits like reduced emissions and improved safety on the roads.

This research adds to the emerging literature on traffic management in developing cities and presents one possible solution for congestion in Kathmandu. The results of this study will be used to give actionable insight into the traffic authorities for synchronized traffic signals, which are going to improve urban mobility with less delay. Ultimately, this research calls for the integration of intelligent traffic management systems into rapidly growing urban areas like Kathmandu.

Keywords: Traffic signal synchronization, Urban traffic management, Traffic congestion, Kathmandu Valley, Traffic delay, Signal timing, Traffic modelling, Vehicle emissions

1. Introduction

The Kathmandu Valley, being the capital region of Nepal, is suffering from a transportation crisis. With growing urbanization, the increased number of vehicles is leading to increased congestion in traffic at important junctions like Maitighar, Thapathali, and Singhadurbar. The present static signal system does not take into consideration the dynamic condition of the traffic flow and results in unnecessary delays during peak hours. A well-coordinated traffic signal system can significantly improve traffic efficiency. It has been generally agreed upon that signal synchronization, or traffic light timing at multiple intersections, significantly decreases traffic congestion in urban settings.

Globally, signal synchronization has proven to reduce travel times, consume less fuel, and cause less emissions. But, locally in Kathmandu, such limited attempts have been made with unexplored depth in its study. This paper thus revisits and evaluates current studies on the synchronization of traffic signals and how their methodologies

might be adopted for application to the Kathmandu Valley. Furthermore, MATLAB will be utilized as a tool for testing different synchronization algorithms to obtain an in-depth understanding of how signal coordination can reduce delays in traffic flow.

The review intends to focus on three key objectives synthesized from studies on advanced traffic management systems: evaluation of the effectiveness of the synchronization of traffic signals; methodologies suitable for applying synchronization in Kathmandu; and simulation of the impact using MATLAB.

2. Objectives

The study on the effectiveness of traffic signal synchronization in mitigating urban traffic delays within the Kathmandu Valley is done to quantify the reduction in travel time, fuel consumption, and air pollution levels.

3. Literature Review

3.1 Traffic Signal Synchronization and Adaptive Control

Signal synchronization has been one of the most researched aspects in the field of ITS. In this regard, Banerjee, Chang, and Zhang (2022) discussed V2I communication systems where intelligent vehicles and sensors are integrated with traffic lights. This enables real-time adjustment of signal timings as per the actual traffic volume. The outcome indicated a 20% average enhancement in the flow of traffic in urban environments that were equipped with V2I technologies.

Wang et al. (2023) propose a DT model in another related study, where virtual replicas of actual traffic systems provide real-time data on the optimization of traffic signal timings. The simulations carried out in MATLAB yielded a delay reduction of 30%, and thus this could be of great use for complex urban networks.

3.2 Machine Learning Approaches for Signal Synchronization

Liu, Peng, and Wang (2020) used reinforcement learning to optimize traffic signal timing. The machine learning model enabled the signal system to be dynamic with respect to any fluctuating traffic condition. Reinforcement learning reduced vehicle stops by 15% and travel time by 20%, according to the research conducted with the use of the MATLAB toolbox on machine learning. This method is useful when the pattern of traffic flow becomes unpredictable and is hence considered suitable for the traffic problems in Kathmandu's congested intersections.

In a related study, Zhou and Qian (2021) compared the performance of traditional static signal systems against machine learning algorithms that adjust timings based on historical and real-time traffic data. Their results showed that machine learning provided more accurate adjustments, reducing delays by 20% at major urban intersections. The adaptability of machine learning systems provides a significant advantage over static or semi-static systems, especially in unpredictable environments like Kathmandu.

3.3 Real-Time Data and Microsimulation Models

Huang, He, and Liu (2020) studied the usage of real-time data for adaptive traffic signal control, utilizing the input of cameras and sensors in order to change the dynamic traffic light setting. They simulated the above using MATLAB and came out with delays being reduced by 25%. The study emphasized the key features of real-time data usage on traffic congestion management; this is an essential basis upon which synchronization can be installed for the Kathmandu network of roadways.

Similarly, Kim, Park, and Seo (2021) used microsimulation models to test the effects of synchronized traffic signals. Their results indicated a 25% reduction in travel times, particularly in peak hours of traffic. Microsimulation provides a more detailed understanding of traffic flow and thus allows for the testing of various synchronization algorithms under real-time scenarios. The simulation tools of MATLAB were very efficient in testing these scenarios and optimizing signal timings based on traffic volume.

Chen et al. (2019) proposed the application of genetic algorithms in optimizing traffic signal timings. This approach tested different traffic scenarios and adjusted signal timings according to historical and real-time data. The results indicated that there was a reduction of 15-20% in vehicle delays within a complex urban network.

Genetic algorithms were thus found to be quite effective for large-scale optimization of traffic signals. These findings are quite applicable in cities like Kathmandu, where uncoordinated signals lead to massive delays.

Singh & Kaur (2021) analyzed signal coordination on arterial roads using the Synchro software for traffic modeling. The result showed a reduction in stops by vehicles by about 25% and an improvement in travel time by 10-15%, especially during peak hours. The authors concluded that signal coordination along busy corridors is very important and thus applies to the arterial roads of Kathmandu.

Zhou et al. (2020) developed an IoT-based real-time traffic signal control system that dynamically adjusted signal timings based on real-time data collected from sensors. Results showed a reduction in waiting time at intersections by up to 30%, illustrating the advantages of real-time continuous monitoring of flow conditions. This method would therefore be suitable for traffic conditions at urban areas, like those in Kathmandu, that cannot be predicted.

Patel et al. (2022) discussed the environmental benefit of traffic signal synchronization, such as fuel consumption and CO2 emission. The researchers reported a 15% reduction in fuel consumption, with a 20% reduction in CO2 emission, thus indicating the environmental advantage of synchronized signals along with improved flow.

3.4 YOLO Algorithm in Traffic Studies

Among these, the YOLO algorithm, which can realize real-time object detection, has been given considerable attention in traffic management research. Redmon et al. (2016) introduced YOLO, a deep learning-based object detection framework that processes an entire image in one pass and thus is very efficient for real-time applications. Its adaptability to detect multiple object classes simultaneously makes it ideal for traffic-related studies, including vehicle detection and counting.

Zhao et al. (2020) implemented the YOLOv3 algorithm to analyze urban traffic flows using video data collected at signalized intersections. The study demonstrated that YOLOv3 achieved high accuracy (above 90%) in detecting vehicles in real-world urban environments, even under challenging conditions like varying lighting and occlusions. The findings underscore the algorithm's robustness in traffic scenarios.

Gupta et al. (2021) used YOLOv4 for vehicle classification and counting at urban intersections with highly dense populations. Their results have shown that the algorithm could process video feeds in real time with minimal computational resources while maintaining high detection accuracy. This approach considerably reduces the errors associated with manual counting and hence provides reliable data to optimize traffic signal timings.

Khan et al. (2022) used YOLOv5 for vehicle detection in dynamic urban environments and integrated the method into adaptive traffic signal systems. They underlined that YOLOv5 could manage video data coming from many crossroads and was very important for finding the peak moments of traffic volume. As a result, the data improved traffic flow, enabled precise signal synchronization.

In the context of Kathmandu Valley, where traffic congestion is a persistent issue, leveraging YOLO for vehicle detection aligns with the need for efficient, automated data collection methods. The integration of YOLO into traffic studies ensures accurate, large-scale data analysis, enabling more effective traffic signal synchronization.

4. Research Methodology

4.1 Data Collection

➤ CCTV Data Analysis: Video from CCTV cameras installed at the respective intersections shall be leveraged for data collection, which will be further used to analyze vehicle flow and traffic volume data.

4.2 MATLAB Simulation Process

I. Model Development: The Traffic Toolbox in MATLAB shall be utilized to model the study area's traffic network, considering volumes of traffic, geometry of roads, and existing timings of signals at major junctions.

II.Signal Timing Optimization: The optimization algorithms in MATLAB will be utilized to synchronize the signal timings at multiple intersections. The result will be the minimum stop-and-go traffic, and hence, minimum delays.

III.Scenario Testing: A number of scenarios are going to be simulated, such as peak hours and different volumes of traffic, to determine how different synchronization techniques perform. Adaptive control algorithms such as machine learning will be implemented to compare their performance with conventional methods.

IV.Result Analysis: The simulated results will be compared to baseline data to evaluate the reduction in travel time, queue length, and overall delay.

4.3 Statistical Analysis

4.3.1. Data Entry and Management:

➤ Vehicle Flow and Delay Data: Input traffic data such as vehicle counts, delays, and travel times into SPSS. This includes data from traffic observations, CCTV, or other sources.

➤ Categorization: The use of SPSS in categorizing data on variables such as peak vs. non-peak hours, signalized vs. non-signalized intersections, or synchronized vs. non-synchronized signals.

4.3.2. Descriptive Statistics:

➤ Summarizing Data: SPSS is used to calculate simple descriptive statistics that include mean, median, mode, and standard deviation to summarize traffic delays before and after synchronization.

➤ Traffic Flow Characteristics: Frequency distributions and cross-tabulations are generated to understand the pattern of traffic flow and delays.

4.3.3. Comparison of Means (T-Tests, ANOVA):

➤ Before and After Synchronization: The paired t-test or independent t-test in SPSS will be conducted to compare traffic delays before and after synchronization to see if the change in delays is statistically significant.

➤ Multiple Intersections Comparison: When several intersections are to be compared, such as some with synchronization and others not, the ANOVA is used to test if there is a significant difference in the delay variations across groups of intersections.

➤ Correlation: Pearson correlation in SPSS examines the relationship between variables representing the flow of traffic, such as volume of traffic and intersection delay with signal timing. It will help to ascertain whether increased vehicle volume is associated with longer delays.

➤ Regression Analysis: Linear or multiple regression could be used to model the relationship between dependent variables, such as traffic delays, and independent variables, such as vehicle flow or signal timings. This helps quantify how much delay is reduced due to synchronization.

4.3.5. Hypothesis Testing:

➤ Testing Effectiveness of Synchronization: Using SPSS to test hypotheses that can confirm whether synchronization significantly reduces traffic delays. Testing may be done for hypotheses such as:

➤ Null Hypothesis (H0): Synchronization does not reduce traffic delays significantly

➤ Alternative Hypothesis (H1): Synchronization significantly reduces traffic delays

4.3.6 Chi-Square Test

➤ To assess the relationship of synchronization with traffic delay frequencies.

4.3.7. Visualization:

➤ The charts and graphs -including histograms, bar charts, and scatter plots- that will be generated through SPSS will visually represent traffic delay trends before and after synchronization. These will probably facilitate the understanding of the data as well as present it more succinctly.

4.4 Integrating YOLO Algorithm for Vehicle Detection and Counting

The video-recorded data of the traffic flow in these junctions will be analyzed using the YOLO algorithm as part of the traffic data collection for the study.

The methodology involves following processes:

4.4.1 Video Data Collection: Traffic videos will be recorded at selected signalized intersections in Kathmandu Valley using stationary cameras during peak and non-peak hours.

The focus will be on intersections both before and after traffic signal synchronization to evaluate its impact.

4.4.2 Preprocessing: The recorded video data will be converted into a format compatible with YOLO.

Frames will be extracted at regular intervals to reduce processing time while retaining sufficient data granularity.

4.4.3 YOLO Implementation: Model Selection: YOLOv5 will be selected because it has very high accuracy with computational efficiency for real-time detection.

4.4.4 Training and Fine-Tuning: A pre-trained YOLO model will be fine-tuned using a dataset of annotated traffic images specific to the Kathmandu Valley context, such as local vehicle types like motorbikes, minibuses, and trucks.

4.4.5 Vehicle Detection and Counting: YOLO will process each frame for the detection and classification of vehicles into categories, such as cars, buses, and motorbikes.

Count and log the number of vehicles passing through each intersection in pre-defined time intervals.

4.4.6 Data Validation: Comparison of YOLO-detected counts with manually collected data for validation of algorithm accuracy.

4.4.7 Traffic Flow Analysis:

Calculation of the metrics such as traffic volume, average delays, and waiting times at intersections will be determined by the counts recorded using YOLO.

These metrics will be used as inputs for the evaluation of the impacts of signal synchronization.

Traffic Signal Synchronization

4.4.8 Integration: The YOLO-obtained data on the flow of vehicles will be integrated with the MATLAB simulations to model how synchronization will affect the reduction in delays.

Data Collection
MATLAB Simulation Process
Statistical Analysis
Integrating YOLO Algorithm for Vehicle Detection and Counting

Fig -1: Flowchart of Research Methodology

5. Expected Results

With the installation of synchronized traffic signals in Kathmandu, delays at major junctions are bound to reduce considerably. Based on various studies reviewed, the outcomes that are foreseen would include:

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- Up to a 30% reduction in delays in travel during peak hours,
 - Smoothing of traffic flow with increased fuel efficiency on account of reduced numbers of stops,
 - Reducing emissions,
 - Reduced queue lengths at junctions for an all-round better mobility experience in Kathmandu.

6. Conclusion

The prospect of traffic signal synchronization in reducing urban traffic delays, particularly in areas that have become perennially congestive, such as Kathmandu Valley, remains very promising. By synchronizing the traffic signals of successive intersections, it ensures a smooth flow of traffic, minimizing the frequency of vehicle stops and minimizing delay conditions. This, according to different global studies, increases fuel efficiency with reduced emissions, ensuring safety on the roads, particularly in heavily populated urban cities.

In the context of Kathmandu, where traffic congestion is a growing concern, the implementation of signal synchronization could lead to meaningful improvements in mobility and intersection efficiency. This review identifies adaptive traffic management systems as systems that respond to real-time traffic conditions and improve the performance of existing signal networks.

Therefore, the application of synchronized traffic signals can be one of the effective solutions to the ever-increasing traffic problem in Kathmandu Valley. This will not only yield benefits in terms of reduced delays but also in terms of improved environmental outcomes. Insights from global research can thus help in designing and implementing synchronization strategies that are tailored to Kathmandu's unique traffic challenges, thereby contributing to more sustainable and efficient urban transportation.

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