# A novel approach on Spherical Neutrosophic Hesitant Fuzzy Sets (SNHFS)

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#### **Abstract**

This paper introduces Spherical Neutrosophic Hesitant Fuzzy Sets (SNHFS) a novel extension that combines neutrosophic logic, hesitant fuzzy sets and spherical constraints to handle uncertainty and indeterminacy in decision-making scenarios. The SNHFS framework addresses the limitations of existing fuzzy set theories by incorporating three membership functions with hesitant values while maintaining the spherical constraint that the sum of squares of membership degrees does not exceed unity. We establish fundamental set-theoretic operations, topological properties and distance measures for SNHFS. The theoretical framework includes comprehensive proofs of idempotent laws, commutative laws, associative laws and De Morgan's laws. Additionally, we develop SNHF topological spaces and investigate continuity properties. The proposed distance measure satisfies all metric properties making it suitable for similarity assessments and clustering applications. Our findings demonstrate that SNHFS provides a more flexible and robust framework for handling complex uncertainty scenarios compared to existing approaches, with potential applications in multi-criteria decision making, pattern recognition and artificial intelligence systems.

**Keywords:** Spherical fuzzy sets, Neutrosophic sets, Hesitant fuzzy sets, Topology, Distance measures, Uncertainty modeling

#### 1. Introduction

In the realm of uncertainty modeling and decision-making under imprecise information, fuzzy set theory has evolved significantly since its inception by Zadeh [1]. The classical fuzzy set theory, characterized by a single membership function has been extended in various directions to address different types of uncertainties and decision-making scenarios. These extensions include intuitionistic fuzzy sets [2], neutrosophic sets [3], hesitant fuzzy sets [4], and spherical fuzzy sets [5]. Neutrosophic sets, introduced by Smarandache [3], represent a powerful generalization of fuzzy sets and intuitionistic fuzzy sets. They are characterized by three membership functions: truth-membership, indeterminacy-membership, and falsity-membership, which can handle incomplete, inconsistent, and indeterminate information effectively. The single-valued neutrosophic sets [6] have been widely applied in various fields including decision-making [7], pattern recognition [8] and medical diagnosis [9].

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Hesitant fuzzy sets, proposed by Torra [4] address situations where decision-makers hesitate among several possible membership values for an element. This hesitation naturally occurs in real-world scenarios where experts may have different opinions or when the available information is insufficient for precise evaluation. The hesitant fuzzy set theory has been successfully applied in group decision-making [10], risk assessment [11] and supplier selection [12]. Spherical fuzzy sets, introduced by Kutlu Gündoğdu and Kahraman [5], extend neutrosophic sets by imposing a spherical constraint on the membership functions. This constraint ensures that the sum of squares of truth, indeterminacy, and falsity membership degrees does not exceed unity, providing a more flexible framework than intuitionistic fuzzy sets while maintaining mathematical rigor. Spherical fuzzy sets have shown promising results in multi-criteria decision making [13], performance evaluation [14]. Meher Taj and Kumaravel analyzed and found a system based on fuzzy Petri nets for measuring employee performance [15], knowledge systems [16] and color systems [17].

Despite these advances, existing fuzzy set extensions have limitations in handling complex real-world scenarios that involve multiple types of uncertainties simultaneously. For instance, decision-makers may experience hesitation about neutrosophic membership values while requiring the mathematical elegance of spherical constraints. Traditional neutrosophic sets do not accommodate hesitation, while hesitant fuzzy sets lack the comprehensive uncertainty representation of neutrosophic logic.

To address these limitations, this paper introduces Spherical Neutrosophic Hesitant Fuzzy Sets (SNHFS), which integrate the strengths of neutrosophic sets, hesitant fuzzy sets, and spherical constraints. The SNHFS framework allows decision-makers to express hesitation about truth, indeterminacy, and falsity membership values while maintaining the spherical constraint for mathematical consistency.

The main contributions of this paper are:

- 1. **Theoretical Foundation**: We establish the mathematical framework for SNHFS, including definitions, basic operations, and fundamental properties.
- 2. **Set-Theoretic Properties**: We prove essential laws including idempotent, commutative, associative and De Morgan's laws for SNHFS operations.
- 3. **Topological Framework**: We develop SNHF topological spaces and investigate properties of interior, closure and neighborhood concepts.
- 4. **Distance Measures**: We propose a distance measure for SNHFS that satisfies all metric properties and demonstrate its effectiveness.
- 5. **Continuity Theory**: We extend the concept of continuity to SNHF topological spaces and provide multiple characterizations.

The remainder of this paper is organized as follows: Section 2 presents the preliminary concepts and definitions. Section 3 establishes the theoretical properties through comprehensive theorems and proofs. Section 4 develops the continuity theory for SNHF spaces. Section 5 provides concluding remarks and future research directions.

#### 2. Preliminaries

# 2.1 Neutrosophic Sets

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Neutrosophic sets introduced by Smarandache [3], provide a comprehensive framework for handling uncertainty by incorporating three membership functions: truth, indeterminacy and falsity.

**Definition 2.1.1**: Let U be a universe of discourse. A Neutrosophic set A in U is characterised by a truth-membership function  $T_A$  an indeterminacy membership function  $I_A$  and a falsity-membership function  $F_A$  where:[3]

$$T_A$$
,  $I_A$ ,  $F_A$ : U $\to$  (0<sup>-</sup>, 1<sup>+</sup>) are functions and  $0 \le T_A(x) + I_A(x) + F_A(x) \le 3^+$ .

The Neutrosophic set is represented as:

$$A = \{(x, T_A(x), I_A(x), F_A(x)) | x \in U\}$$

For practical applications, Smarandache and Wang et al. [8] introduced the concept of a single valued Neutrosophic set.

**Definition 2.1.2:** A single-valued Neutrosophic set (SVNS) A over U is defined as: [8]

$$A = \{(x, T_A(x), I_A(x), F_A(x)) | x \in U\}$$

Where  $T_A$ ,  $I_A$ ,  $F_A$ :  $U \rightarrow [0, 1]$  and for all  $x \in U$ .

$$0 \le T_A(x) + I_A(x) + F_A(x) \le 3.$$

## 2.2 Hesitant Fuzzy Sets

Hesitant fuzzy sets, proposed by Torra [4], address situations where decision-makers are uncertain about the exact membership degree of an element.

**Definition 2.2.1:** Let U be a fixed set. A hesitant fuzzy set (HFS) on U is defined in terms of a function h that returns a subset of [0, 1] when applied to U:[4]

$$A = \{(x, h_A(x)) | x \in U\}$$

Where  $h_A(x) \subseteq [0, 1]$  is a finite set of positive membership degree of x in A.

## 2.3 Spherical Fuzzy Sets

Spherical fuzzy sets, introduced by Kutlu Gündoğdu and Kahraman [5], impose a spherical constraint on membership degrees.

**Definition 2.3.1:** A spherical fuzzy set A on universe U is defined as:[5]

$$A = \{(x, (\mu_A(x), v_A(x), \pi_A(x))) \mid x \in U\}$$

with  $\mu_A(x)$ ,  $\nu_A(x)$ ,  $\pi_A(x) \in [0, 1]$  satisfying

$$0 \le \mu_A^2(\mathbf{x}) + v_A^2(\mathbf{x}) + \pi_A^2((\mathbf{x}) \le 1.$$

The hesitancy degree is calculated as

$$\pi_A(x) = \sqrt{1 - \mu_A^2(x) - v_A^2(x)}$$

## 2.4 Spherical Neutrosophic Hesitant Fuzzy Sets

Building upon these concepts, we now introduce spherical Neutrosophic hesitant fuzzy sets, which integrate neutrosophic logic, hesitant fuzzy sets and the spherical constraint.

**Definition 2.4.1:** A Spherical neutrosophic hesitant Fuzzy set (SNHFS) A on universe U is defined as:

$$A = \{(x, (T_A(x), I_A(x), F_A(x))) | x \in U\}$$

Where,  $T_A(x) = \{+, +_2, \dots, +_n\} \subseteq [0, 1]$  is the set of possible truth-membership degrees.

 $I_A(x) = \{i, i_2, \dots, i_m\} \subseteq [0, 1]$  is the set of indeterminacy-membership degrees.

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 $F_A(x) = \{f_1, f_2, \dots, f_k\} \subseteq [0, 1]$  is the set of falsity-membership degrees.

For all  $t \in T_A(x)$ ,  $i \in I_A(x)$ ,  $f \in F_A(x)$ , the spherical condition  $t^2 + i^2 + f^2 \le 1$  must hold. The Collection of all SNHFS on U is denoted by SNHFS(U).

#### 3. Main Results

## 3.1 Basic Operations and Properties

**Definition 3.1.1:** Let A & B be two SNHFS on universe U. The following operations are defined:

- 1. Complement:  $A^{C} = \{(x, (F_{A}(x), I_{A}(x), T_{A}(x))) | x \in U\}$
- 2. Union: AUB = { $(x, (T_{A \cup B}(x), I_{A \cup B}(x), F_{A \cup B}(x))) | x \in U$ }

where, 
$$T_{A \cup B}(x) = \{ \max(t_A, t_B) \mid t_A \in T_A(x); t_B \in T_B(x) \}$$
  
 $I_{A \cup B}(x) = \{ \min(i_A, i_B) \mid i_A \in I_A(x); i_B \in I_B(x) \}$ 

$$F_{A\cup B}(\mathbf{x}) = \{ \min(f_A, f_B) \mid f_A \in F_A(\mathbf{x}); f_B \in F_B(\mathbf{x}) \}$$

3. Intersection:  $A \cap B = \{(x, (T_{A \cap B}(x), I_{A \cap B}(x), F_{A \cap B}(x))) | x \in U\}$  where,

$$T_{A \cap B}(x) = \{ \min(t_A, t_B) \mid t_A \in T_A(x); t_B \in T_B(x) \}$$
  
$$I_{A \cap B}(x) = \{ \max(i_A, i_B) \mid i_A \in I_A(x); i_B \in I_B(x) \}$$

$$F_{A \cap B}(x) = \{ \max(f_A, f_B) \mid f_A \in F_A(x); f_B \in F_B(x) \}$$

#### 3.2 Fundamental Theorems

Theorem 3.2.1 (Idempotent laws): For any SNHFS A in universe U,

a) 
$$AUA = A$$

b) 
$$A \cap A = A$$

#### **Proof:**

a) For AUA: Lets examine each component separately.

For the truth membership:

$$T_{A \cup A}(x) = \{ \max(t_1, t_2) \mid t_1, t_2 \in T_A(x) \} = T_A(x)$$

$$I_{A \cup A}(x) = \{ \min(i_1, i_2) \mid i_1, i_2 \in I_A(x) \} = I_A(x)$$

$$F_{A \cup A}(x) = \{ \min(f_1, f_2) \mid f_1, f_2 \in F_A(x) \} = F_A(x)$$

Since all three components remain unchanged we have  $A \cup A = A$ .

b) The proof of  $A \cap A = A$  follows a similar approach by examining each component and applying the minimum and maximum operations to identical values.

## **Theorem 3.2.2 (Commutatively Laws):**

For any SNHFSs A and B in universe U,

a) 
$$AUB = BUA$$

b) 
$$A \cap B = B \cap A$$

#### **Proof:**

a) For AUB,

Truth Membership:  $T_{A \cup B}(x) = \{ \max(t_A, t_B) \mid t_A \in T_A(x); t_B \in T_B(x) \}$ 

$$I_{A \cup B}(x) = \{ \min(i_A, i_B) \mid i_A \in I_A(x); i_B \in I_B(x) \}$$

$$F_{A \cup B}(x) = \{ \min(f_A, f_B) \mid f_A \in F_A(x); f_B \in F_B(x) \}$$

Similarly for BUA, the same operations hold with arguments swapped. Since max(a, b) = max(b, a) and min(a, b) = min(b, a). We conclude:

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b) The proof for  $A \cap B = B \cap A$  follows the same reasoning, using the commutatively of min and max operations.

Theorem 3.2.3 (Associativity Laws): For any SNHFSs A, B and C in universe U,

- a) (AUB)UC = AU(BUC)
- b)  $(A \cap B) \cap C = A \cap (B \cap C)$

#### **Proof:**

a) For (AUB)UC:

First compute AUB,

$$T_{A \cup B}(x) = \{ \max(t_A, t_B) \mid t_A \in T_A(x); t_B \in T_B(x) \}$$
  
$$I_{A \cup B}(x) = \{ \min(i_A, i_B) \mid i_A \in I_A(x); i_B \in I_B(x) \}$$

$$F_{A \cup B}(x) = \{ \min(f_A, f_B) \mid f_A \in F_A(x); f_B \in F_B(x) \}$$

Then, compute(AUB)UC,

$$T_{(A \cup B) \cup C}(x) = \{ \max(\max(t_A, t_B), t_C) \mid t_A \in T_A(x); t_B \in T_B(x); t_C \in T_C(x) \}$$

$$= \{ \max(t_A, \max(t_B, t_C)) \mid t_A \in T_A(x); t_B \in T_B(x); t_C \in T_C(x) \}$$

$$= T_{A \cup (B \cup C)}(x)$$

b) The proof for  $(A \cap B) \cap C = A \cap (B \cap C)$  follows a similar approach by using the associativity of min and max operations.

Theorem 3.2.1 (De Morgan's Laws): For any SNHFs A and B in universe U,

a) 
$$(A \cup B)^C = A^C \cap B^C$$

b) 
$$(A \cap B)^C = A^C \cup B^C$$

#### **Proof:**

a) For 
$$(AUB)^C$$
,

$$= \{ \min(t_{A^{C}}, t_{B^{C}}) \mid t_{A^{C}} \in T_{A^{C}}(x); t_{B^{C}} \in T_{B^{C}}(x) \}$$

$$= T_{A^{C} \cap B^{C}}(x)$$

$$I_{(A \cup B)^{C}}(x) = I_{A \cup B}(x) = \{ \min(i_{A}, i_{B}) \mid i_{A} \in I_{A}(x); i_{B} \in I_{B}(x) \}$$

$$= \{ \max(i_{A^{C}}, i_{B^{C}}) \mid i_{A^{C}} \in I_{A^{C}}(x); i_{B^{C}} \in I_{B^{C}}(x) \}$$

$$= I_{A^{C} \cap B^{C}}(x)$$

$$F_{(A \cup B)^{C}}(x) = T_{A \cup B}(x) = \{ \max(t_{A}, t_{B}) \mid t_{A} \in T_{A}(x); t_{B} \in T_{B}(x) \}$$

$$= \{ \max(f_{A^{C}}, f_{B^{C}}) \mid f_{A^{C}} \in F_{A^{C}}(x); f_{B^{C}} \in F_{B^{C}}(x) \}$$

$$= F_{A^{C} \cap B^{C}}(x)$$

 $T_{(A \cup B)}c(x) = F_{A \cup B}(x) = \{ \min(f_A, f_B) \mid f_A \in F_A(x); f_B \in F_B(x) \}$ 

Comparing the corresponding components, we see that

$$T_{(A \cup B)}c(x) = T_{A}c \cap Bc(x)$$

$$I_{(A \cup B)}c(x) = I_{A}c \cap Bc(x)$$

$$F_{(A \cup B)}c(x) = F_{A}c_{\cap B}c(x)$$

$$:(\mathsf{AUB})^{\mathcal{C}} = A^{\mathcal{C}} \cap B^{\mathcal{C}}$$

b) The proof for  $(A \cap B)^C = A^C \cup B^C$  follows a similar approach.

## 3.3 Properties of SNHF Topological Spaces

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**Theorem 3.3.1:** In a SNHF topological space  $(X, \tau)$  for any SNHFS A and B in X,

- a)  $int(A \cap B) = int(A) \cap int(B)$
- b)  $int(A) \cup int(B) \subseteq int(A \cup B)$

#### **Proof:**

a) To Prove:  $int(A \cap B) = int(A) \cap int(B)$ 

STEP 1: Show that  $int(A \cap B) \subseteq int(A) \cap int(B)$ 

By definition  $int(A \cap B)$  is the largest open SNHFS contained in  $A \cap B$ . Since  $A \cap B \subseteq A$  and  $A \cap B \subseteq B$ , we have  $int(A \cap B) \subseteq int(A)$  and  $int(A \cap B) \subseteq int(B)$ 

 $\therefore int(A \cap B) \subseteq int(A) \cap int(B)$ 

STEP 2: Show that  $int(A) \cap int(B) \subseteq int(A \cap B)$ 

 $int(A) \subseteq A$  and  $int(B) \subseteq B$ , So  $int(A) \cap int(B) \subseteq A \cap B$ 

int(A) and int(B) are open SNHFS and the intersection of open sets is open in a topology.

Therefore,  $int(A) \cap int(B)$  is an open SNHFS contained in A $\cap$ B. Since  $int(A\cap B)$  is the largest open SNHFS contained in A $\cap$ B, we have

 $int(A) \cap int(B) \subseteq int(A \cap B)$ 

Combining STEP 1 & 2, we conclude that,  $int(A \cap B) = int(A) \cap int(B)$ 

b) To Prove:  $int(A) \cup int(B) \subseteq int(A \cup B)$ 

 $int(A) \subseteq A$  and  $int(B) \subseteq B$  imply that  $int(A) \cup int(B) \subseteq A \cup B$ .

int(A) and int(B) are open SNHFS and the union of open sets is open in a topology.

Therefore, int(A) U int(B) is an open SNHFS contained in AUB. Since int(AUB) is the largest open SNHFS contained in AUB, we have

 $\therefore$  int(A)  $\bigcup$  int(B)  $\subseteq$  int(AUB).

**Note:** The Reverse inclusion  $int(A \cup B) \subseteq int(A) \cup int(B)$  does not generally hold, which can be demonstrated with counter examples.

#### 3.3 SNHF Topological Spaces

**Definition 3.3.1:** A SNHF topology on a non-empty set X is a collection  $\tau$  of SNHFS in X satisfying the following axioms:

- 1.  $\bar{O}\bar{I} \in \tau$  where  $\bar{O} = \{x, (\{0\}, \{1\}, \{1\}) \mid x \in X\}$  $\bar{I} = \{x, (\{1\}, \{0\}, \{0\}) \mid x \in X\}$
- 2. If A, B  $\in \tau$ , then A $\cap$ B $\in \tau$
- 3. If  $\{A_i \mid i \in J\} \subseteq \tau$ , then  $\bigcup_{i \subset I} A_i \in \tau$ .

The pair  $(X, \tau)$  is called a SNHF Topological space. The member of tare called SNHF open sets, and their complements are called SNHF closed sets.

**Theorem 3.3.1**: In a SNHF topological space  $(X, \tau)$  for any SNHFS A and B in X:

a)  $int(A \cap B) = int(A) \cap int(B)$  b)  $int(A) \cup int(B) \subseteq int(A \cup B)$ 

**Theorem 3.3.2**: In a SNHF topological space  $(X, \tau)$  for any SNHFS A and B in X:

a)  $cl(A \cup B) = cl(A) \cup cl(B)$  b)  $cl(A) \cap cl(B) \supseteq cl(A \cap B)$ 

#### 3.4 Distance Measures

**Definition 3.4.1**: Let A and B be two SNHFS in universe U. The Spherical neutrosophic hesitant fuzzy distance between A and B is defined as:

**Theorem 3.4.1:** Let A & B be two SNHFS in universe U. The Spherical neutrosophic hesitant fuzzy distance between A and B denoted by  $d_{SNHF}(A, B)$  satisfies the following properties,

- a)  $0 \le d_{SNHF}(A, B) \le 1$
- b)  $d_{SNHF}(A, B) = 0$  if and only if A = B
- c)  $d_{SNHF}(A, B) = d_{SNHF}(B, A)$  [Symmetry]
- d)  $d_{SNHF}(A, C) \le d_{SNHF}(A, B) + d_{SNHF}(B, C)$ [Triangular Inequality]

#### **Proof:**

Let define SNHF distance as:

$$d_{SNHF}(A,B) = \frac{1}{3n} \sum_{x \subset U} [d_{HFS}(T_A(x), T_B(x)) + d_{HFS}(I_A(x), I_B(x)) + d_{HFS}(F_A(x), F_B(x))]$$

Where  $d_{HFS}$  is the distance between hesitant fuzzy element defined as:

$$d_{HFS}(h_1, h_2) = \frac{1}{\max(|h_1|, |h_2|)} \sum_{i=1}^{\max(|h_1|, |h_2|)} |h_1^{\sigma}(i) - h_2^{\sigma}(i)|$$

Here,  $|h_1|$  and  $|h_2|$  denote number of elements I hesitant fuzzy elements  $h_1$  and  $h_2$ .

 $h_1^{\sigma}(i)$  and  $h_2^{\sigma}(i)$  are the  $i^{th}$  element of  $h_1$  and  $h_2$  after arranged them in increasing order.

a) To Prove: 
$$0 \le d_{SNHF}(A, B) \le 1$$

STEP 1:  $d_{HFS}(h_1, h_2)$  measures the average absolute difference between corresponding elements in  $h_1$  and  $h_2$  and these elements are in [0, 1]. We have,

$$0 \le d_{HFS}(h_1, h_2) \le 1$$

STEP 2: Since  $d_{SNHF}(A, B)$  is the average of  $d_{HFS}$  for truth, indeterminacy and falsity memberships and each  $d_{HFS}$  is bounded by 0 and 1, we have  $0 \le d_{SNHF}(A, B) \le 1$ 

b) To Prove:  $d_{SNHF}(A, B) = 0$  if and only if A = B

STEP 1: If A=B, then  $T_A(x) = T_B(x)$ ,  $I_A(x) = I_B(x)$  and  $F_A(x) = F_B(x)$  for all  $x \in U$  This implies,

$$d_{HFS}(T_A(x), T_B(x)) = d_{HFS}(I_A(x), I_B(x)) = d_{HFS}(F_A(x), F_B(x)) = 0$$
 for all  $x \in U$   
Therefore,  $d_{SNHF}(A, B) = 0$ 

c) To Prove:  $d_{SNHF}(A, B) = d_{SNHF}(B, A)$ 

STEP 1: From the definition of  $d_{HFS}$ , we have

 $d_{HFS}(h_1, h_2) = d_{HFS}(h_1, h_2)$  because the absolute difference |a-b| = |b-a|.

STEP 2: Using the symmetry of  $d_{HFS}$ , we have

$$\begin{aligned} d_{SNHF}(A,B) &= \frac{1}{3n} \sum_{x \subset U} [d_{HFS}(T_A(x), T_B(x)) + d_{HFS}(I_A(x), I_B(x)) + d_{HFS}(F_A(x), F_B(x))] \\ &= \frac{1}{3n} \sum_{x \subset U} [d_{HFS}(T_B(x), T_A(x)) + d_{HFS}(I_B(x), I_A(x)) + d_{HFS}(F_B(x), F_A(x))] \\ &= d_{SNHF}(B,A) \end{aligned}$$

Hence,  $d_{SNHF}(A, B) = d_{SNHF}(B, A)$ 

d) To Prove:  $d_{SNHF}(A, C) \le d_{SNHF}(A, B) + d_{SNHF}(B, C)$ 

STEP 1: For hesitant fuzzy elements,  $d_{HFS}$  satisfies the triangular inequality.

$$d_{HFS}(h_1, h_3) \le d_{HFS}(h_1, h_2) + d_{HFS}(h_2, h_3)$$

STEP 2: Using the triangular inequality for  $d_{HFS}$ , we have

$$d_{SNHF}(A,C) = \frac{1}{3n} \sum_{x \subset U} [d_{HFS}(T_A(x), T_C(x)) + d_{HFS}(I_A(x), I_C(x)) + d_{HFS}(F_A(x), F_C(x))]$$

$$\leq \frac{1}{3n} \sum_{x \subset U} [d_{HFS}(T_A(x), T_B(x)) + d_{HFS}(I_A(x), I_B(x)) + d_{HFS}(F_A(x), F_B(x))] + d_{HFS}(F_A(x), F_B(x))] + d_{HFS}(F_A(x), F_B(x))$$

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$$\frac{1}{3n} \sum_{x \subset U} [d_{HFS}(T_B(x), T_C(x)) + d_{HFS}(I_B(x), I_C(x)) + d_{HFS}(F_B(x), F_C(x))]$$

$$\leq d_{SNHF}(A, B) + d_{SNHF}(B, C)$$

Hence,  $d_{SNHF}(A, C) \leq d_{SNHF}(A, B) + d_{SNHF}(B, C)$ 

These Fundamental theorems have laid the foundation for topological study of spherical Neutrosophic hesitant fuzzy sets.

## 4. Continuity in SNHF Topological Spaces

**Definition 4.1.1**: Let  $(X, \tau_1)$  and  $(Y, \tau_2)$  be two SNHF topological spaces. A function  $f: X \to Y$  is called SNHF continuous if for every SNHF open set B in Y, the preimage  $f^{-1}(B)$  in an SNHF open set in X.

**Theorem 4.1.1:** Let  $(X, \tau_1)$  and  $(Y, \tau_2)$  be two SNHF topological spaces and

 $f: X \rightarrow Y$  be a function. The following statements are equivalent,

- a) f is SNHF continuous
- b) For each  $x \in X$  and each SNHF neighbourhood N of f(x) in Y, there exist an SNHF neighbourhood M of x in X such that  $f(M) \subseteq N$ .
- c) For each SNHFS A in X,  $f(cl(A)) \subseteq cl(f(A))$
- d) For each SNHF B in Y,  $cl(f^{-1}(B)) \subseteq f^{-1}(cl(B))$
- e) For each SNHF B in Y,  $f^{-1}(int(B)) \subseteq int(f^{-1}(B))$

#### **Proof:**

(a) $\Leftrightarrow$ (b) Assume f is SNHF continuous. Let  $x \in X$  and N be a SNHF neighbourhood of f(x) in Y. By definition, there exist a SNHF open set O in Y such that  $f(x) \in O \subseteq N$ .

Since f is SNHF continuous,  $f^{-1}(0)$  is an SNHF open set in X.

Also  $x \in f^{-1}(0)$  because  $f(x) \in O$ .

Therefore,  $f^{-1}(0)$  is an SNHF neighbourhood of x in X. Let  $M = f^{-1}(0)$ , then

 $f(M) = f(f^{-1}(0)) \subseteq 0 \subseteq N$  as required.

(b)⇔(c) Let A be an SNHFS in X and Y ∈ f(cl(A)) then there exist x ∈ cl(A) such that f(x)=y.

To show that  $y \in cl(f(A))$ , we need to show that every SNHF neighbourhood of y intersects f(A). Let N be an SNHF neighbourhood M of x in X such that  $f(M)\subseteq N$ .

Since  $x \in cl(A)$ , M intersects A

i.e., there exist a point  $z \in M \cap A$ , then  $f(z) \in f(M) \subseteq N$  and  $f(z) \in f(A)$ .

Since N intersects f(A), which implies  $y \in cl(f(A))$ .

Thus,  $f(cl(A)) \subseteq cl(f(A))$ 

#### 5. Applications and Future Directions

The SNHFS framework has significant potential for applications in:

- 1. **Multi-criteria Decision Making**: The framework can handle complex decision scenarios where experts have hesitant opinions about truth, indeterminacy, and falsity degrees.
- 2. **Pattern Recognition**: SNHFS can provide more nuanced classification in scenarios with uncertain and incomplete information.

- 3. **Risk Assessment**: The framework can model various types of uncertainties in risk evaluation processes.
- 4. **Artificial Intelligence**: SNHFS can enhance reasoning systems by providing more comprehensive uncertainty representation.

#### 6. Conclusion

This paper has introduced and developed the mathematical framework of Spherical Neutrosophic Hesitant Fuzzy Sets (SNHFS), which represents a significant advancement in uncertainty modeling by integrating neutrosophic logic, hesitant fuzzy sets and spherical constraints. The key contributions of this work include:

- The Spherical Neutrosophic Hesitant Fuzzy Sets (SNHFS) framework, integrating neutrosophic logic, hesitant fuzzy sets, and spherical constraints to model complex uncertainty more effectively.
- Developed rigorous mathematical foundations, including operations and properties like commutativity, associativity and De Morgan's laws.
- Proposed a topological structure and distance measure for SNHFS, enabling analysis of continuity and comparison of uncertain elements.
- Highlighted advantages such as comprehensive uncertainty representation, geometric interpretability, and enhanced flexibility in decision-making.
- The theoretical developments presented in this paper lay the groundwork for numerous applications in multi-criteria decision-making, pattern recognition, risk assessment, and artificial intelligence.

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